

## SUMMARY

Applied researcher with a PhD in Computer Science and a strong foundation in 3D computer vision. Deep expertise in structure-from-motion, camera modeling, and inverse problems in vision. Research integrates geometric approaches and deep learning to develop principled, generalizable methods. Published in CVPR, ICCV, and 3DV; creator of open-source tools for vision. Proficient in Python, PyTorch, and C++.

## CORE SKILLS

**Languages:** Python, C++, MATLAB

**Frameworks & Libraries:** PyTorch, OpenCV, COLMAP, ONNX, NumPy, SciPy

**Vision & Geometry:** Structure-from-Motion, Inverse Rendering, Depth Estimation, Multi-View Geometry

**Tools:** Git, Docker, Linux, CMake, TensorBoard, Slurm, NGC

## EDUCATION

**University of Maryland**

College Park MD

*Ph.D. in Computer Science*

May 2024

*Bachelor of Science in Mathematics*

May 2015

## WORK EXPERIENCE

**Kitware**

Arlington, VA

*Senior R&D Engineer*

August 2024 – Present

- Improved structure-from-motion pipelines for drone videos, incorporating cross-modality reconstruction from RGB and infrared imagery, with a focus on robustness to challenging camera motion and terrain.
- Developed few-shot, multi-view object detection methods for aerial video, enabling detection under low data regimes.

**NVIDIA Research**

Remote

*Intern, Learning and Perception Research Group*

June 2022 – March 2024

Supervisor: Dr. Orazio Gallo

- Designed depth estimation models that generalize across varying camera fields-of-view; published in 3DV.
- Created **nvTorchCam** (GitHub), an open-source PyTorch-based library for differentiable geometric vision that enables implementing algorithms where camera models can be interchanged without code changes.

**University of Maryland**

College Park, MD

*Research Assistant, Department of Computer Science*

August 2018 – May 2024

Advisor: Dr. David Jacobs

- Conducted research on inverse rendering of objects and human faces, resulting in publications at CVPR, ICCV, and TPAMI.
- Developed methods to recover geometry and material properties by leveraging variations in lighting and viewpoint, forming the core of PhD thesis.

**National Institute of Biomedical Imaging and Bioengineering**

Bethesda, MD

*Postbac IRTA Fellow*

May 2015 – July 2017

- Built MATLAB software for segmenting and tracking cell deformations in time-lapse microscopy, enabling quantitative analysis of mechanical changes in biological tissues.

## COMMUNITY ENGAGEMENT

**AI4All Project Leader**

August 2019 & August 2021

- Mentored underrepresented high school students on a computer vision project using deep learning to classify leaf images.

**Conference Reviewer**

Since 2018

- Regular reviewer for CVPR, ICCV, and ECCV, contributing to peer review in computer vision research.

## SELECTED PUBLICATIONS

- Daniel Lichy**, Hang Su, Abhishek Badki, Jan Kautz, and Orazio Gallo. Field-of-View Agnostic Depth Estimation for Cross-Dataset Generalization. In *International Conference on 3D Vision (3DV)*, 2024. Oral presentation
- Dongxu Zhao, **Daniel Lichy**, Pierre-Nicolas Perrin, Jan-Michael Frahm, and Roni Sengupta. MVPSNet: Fast Generalizable Multi-View Photometric Stereo. In *Proceedings of the IEEE International Conference on Computer Vision (ICCV)*, 2023
- Daniel Lichy**, Roni Sengupta, and David W. Jacobs. Fast Light-Weight Near-Field Photometric Stereo. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)*, 2022
- Daniel Lichy**, Jiaye Wu, Roni Sengupta, and David W. Jacobs. Shape and Material Capture at Home. In *Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR)*, 2021